

# Expected Dose for Seismic GM Scenario Class $A_{SG} : [0, 2 \times 10^4 \text{ yr}]$ (Primary source: WIS-MD-PA-000005 REV 00 AD 01 Sect. J8)

Formal representation and approximation conditional on fixed  $\mathbf{e} = [\mathbf{e}_A, \mathbf{e}_M]$

$$E_A[D_{SG}(\tau | \mathbf{a}, \mathbf{e}_M) | \mathbf{e}_A] = \int_{\mathcal{A}_{SG}} D_{SG}(\tau | \mathbf{a}, \mathbf{e}_M) d_A(\mathbf{a} | \mathbf{e}_A) d\mathbf{a} \cong$$

$\mathbf{a}_{SG} = [n_{SG}, t_1, A_1, t_2, A_2, \dots, t_{n_{SG}}, A_{n_{SG}}]$  CDSP WPs only for  $[0, 2 \times 10^4 \text{ yr}]$

Time damaging event  $\rightarrow$  Fractional Area Damaged

$$p(A_{SG} | \mathbf{e}_A) \sum_{i=1}^n D_{SG}(\tau | \mathbf{a}_i, \mathbf{e}_M) / n \quad \mathbf{a}_i \text{ sampled from } \mathcal{A}_{SG} \text{ consistent with } d_A(\mathbf{a} | \mathbf{e}_A)$$

$\lambda_1 = \lambda_1(\mathbf{e})$  occurrence rate first damaging event

$$\sum_{j=1}^n \left\{ \exp(-\lambda_1 t_j) \lambda_1 \Delta t_j \right\} \left\{ I_1(\tau | t_j, \mathbf{e}) + \sum_{k=j+1}^n I_2(\tau | t_k, \mathbf{e}) \lambda_2 \Delta t_k \right\}$$

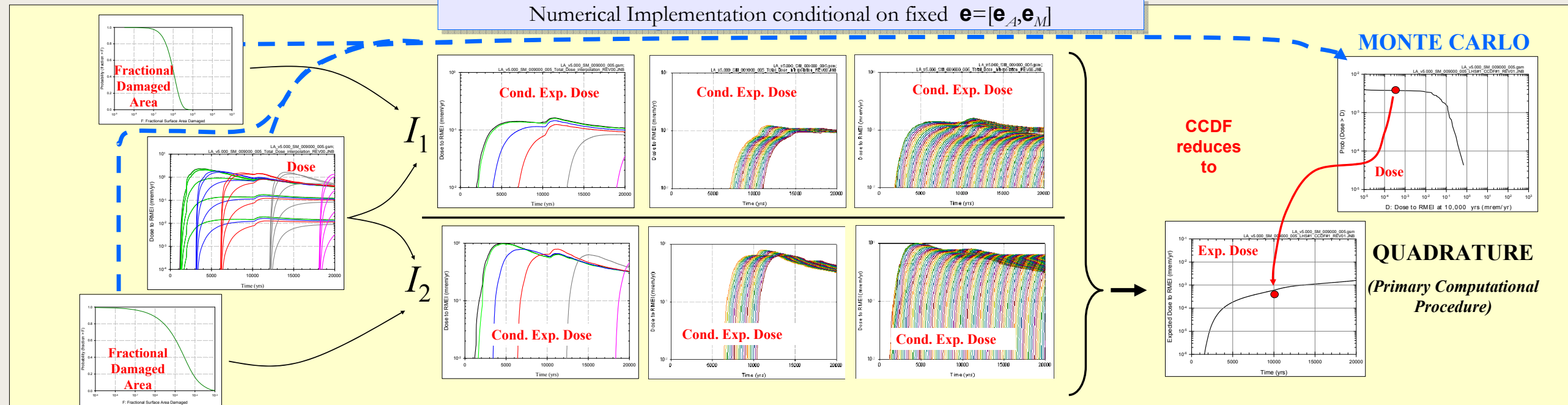
$\lambda_2 = \lambda_2(\mathbf{e})$  occurrence rate subsequent damaging events

Prob. first dam. event in  $[t_{j-1}, t_j]$     Exp. dose at time  $\tau$  from first dam. event at  $t_j$     Exp. dose at time  $\tau$  resulting from dam. events subsequent to first event at  $t_j$

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Quadrature with  $0 = t_0 < t_1 < \dots < t_n = \tau$

Numerical Implementation conditional on fixed  $\mathbf{e} = [\mathbf{e}_A, \mathbf{e}_M]$



Numerical Implementation including uncertainty in  $\mathbf{e} = [\mathbf{e}_A, \mathbf{e}_M]$   
(Based on LHS of size 300 from  $\mathcal{E}$  consistent with  $d_E(\mathbf{e})$ )

